SPACE WEATHER PREDICTION: PRELIMINARY RESULTS USING

MACHINE LEARNING TECHNIQUES

Bala Poduval, Space Science Institute, Boulder, CO Presented at NOAA/SWPC, Boulder, CO 18 January 2018



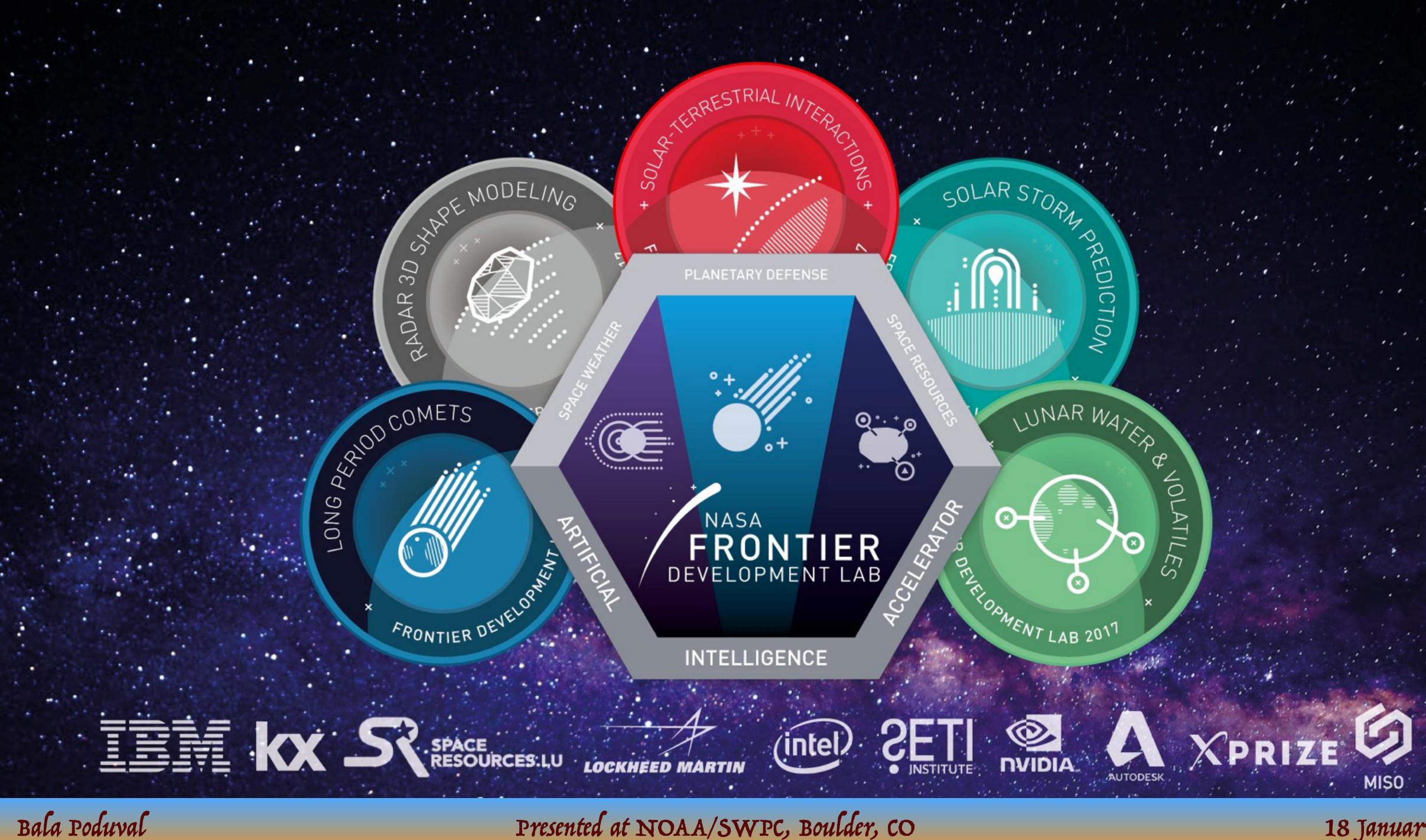
An artificial intelligence (AI) Research and Development accelerator dedicated to bridging knowledge gaps in space programs important to NASA and the future of humanity.

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NASA FDL 2017











socio economic impact

Risk Analysis Post-facto Analysis Forecast Actuary ??

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PROBLEM DEFINITION

Short-term





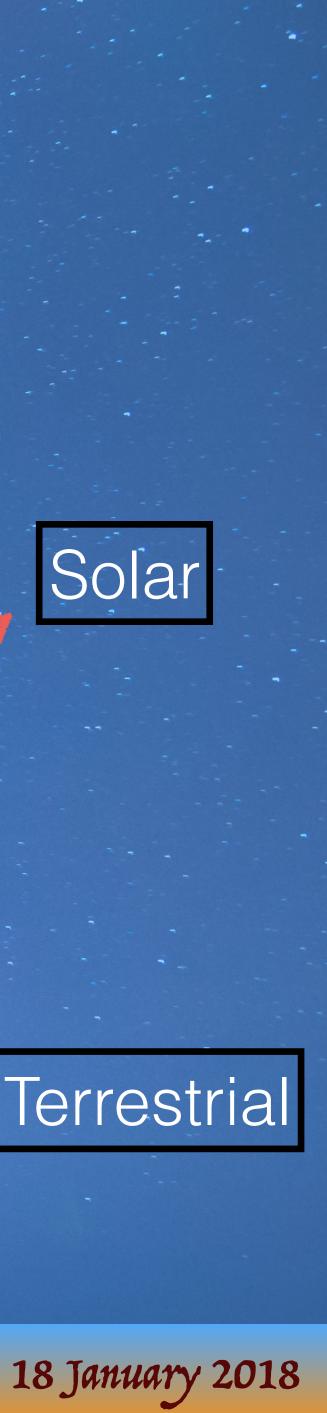
Understand "Cause" & "Effect"

_ong-term

Analyse Data

Non-traditional

(Breakthrough?!)



A data-driven, open source tool for space weather forecasting.

predicts a commonly used index Kp, that represents geomagnetic disturbances.

Open Access Science Data x Al and ML frameworks Better Scientific Insights + Better Predictions

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PROBLEM DEFINITION

Value Proposition:





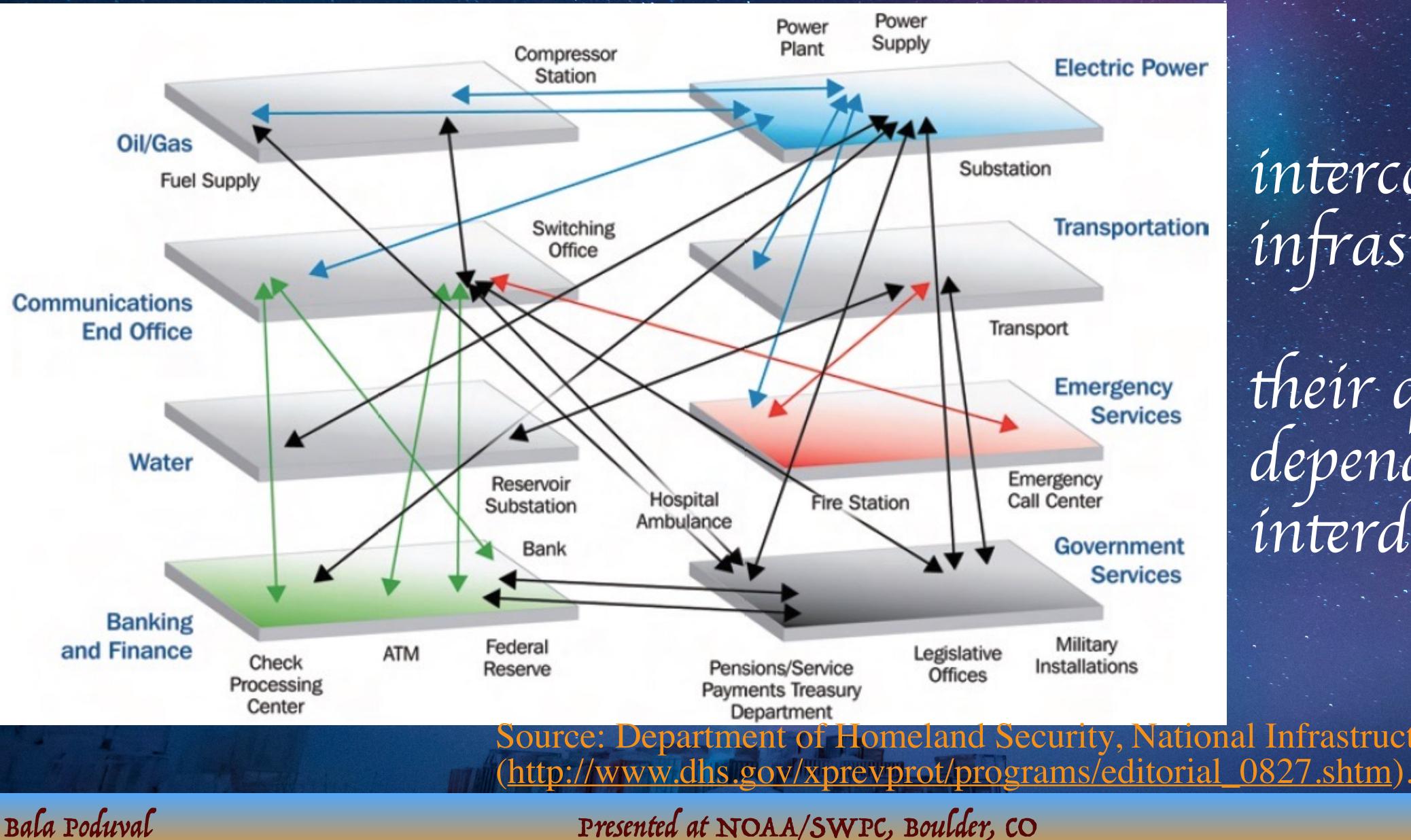
Impact Area	Customer (examples)	Action (examples)	Cost (examples)
Spacecraft (Individual systems to complete spacecraft failure; communications and radiation effects)	 Lockheed Martin Orbital Boeing Space Systems Loral NASA, DoD 	 Postpone launch In orbit - Reboot systems Turn off/safe instruments and/or spacecraft 	 Loss of spacecraft ~\$500M Commercial loss exceeds \$1B Worst case storm - \$100B
Electric Power (Equipment damage to electrical grid failure and blackout conditions)	 U.S. Nuclear Regulatory Commission N. America Electric Reliability Corp. Allegheny Power New York Power Authority 	 Adjust/reduce system load Disconnect components Postpone maintenance 	 Estimated loss ~\$400M from unexpected geomagnetic storms \$3-6B loss in GDP (blackout)
Airlines (Communications) (Loss of flight HF radio communications) (Radiation dose to crew and passengers)	 United Airlines Lufthansa Continental Airlines Korean Airlines NavCanada (Air Traffic Control) 	 Divert polar flights Change flight plans Change altitude Select alternate communications 	 Cost ~ \$100k per diverted flight \$10-50k for re-routes Health risks
Surveying and Navigation (Use of magnetic field or GPS could be impacted)	 FAA-WAAS Dept. of Transportation BP Alaska and Schlumberger 	 Postpone activities Redo survey Use backup systems 	 From \$50k to \$1M daily for single company

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Severe Space Weather Events: Understanding Societal and Economic Impacts: A Workshop Report — The National Academies Press (22 May 2008)





interconnected infrastructures their qualitative dependencies and interdependencies

Source: Department of Homeland Security, National Infrastructure Protection Plan



Power grids — most vulnerable to space weather. during periods of light load with heavy electricity flows from generating plants to load centers — a common practice in the middle of the night during spring & fall

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space weather forecasts is valuable

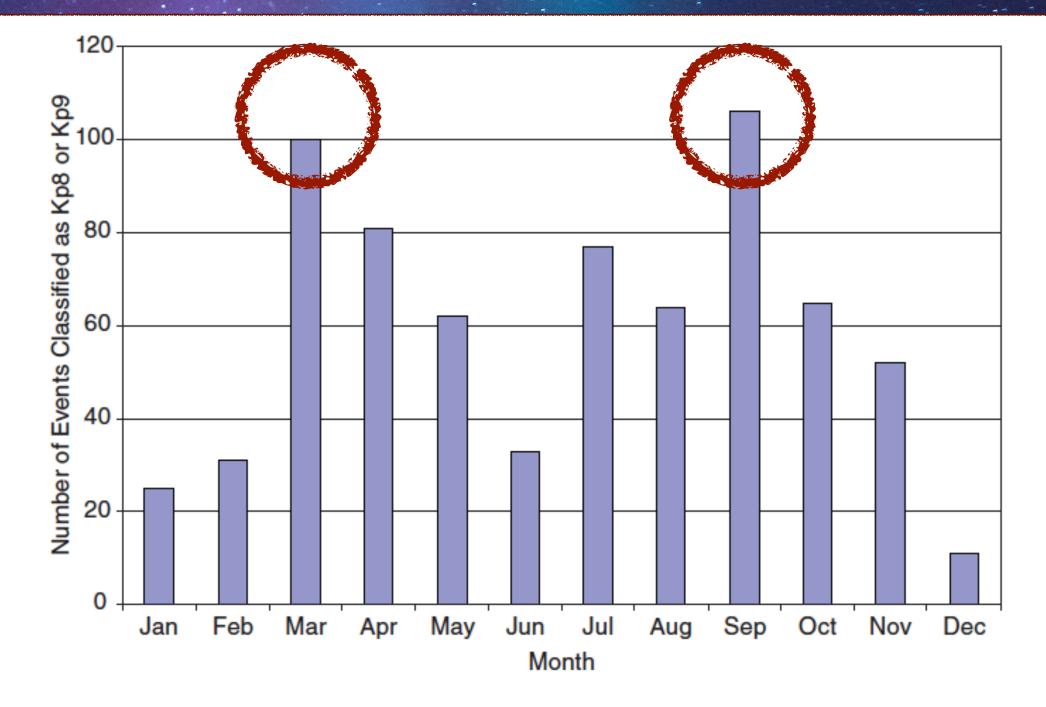


FIGURE 2.3 Incidence of Kp8/Kp9 events by month, 1932-2007, based on an analysis of 222,072 observations. SOURCE: Data from World Data Center for Geomagnetism.





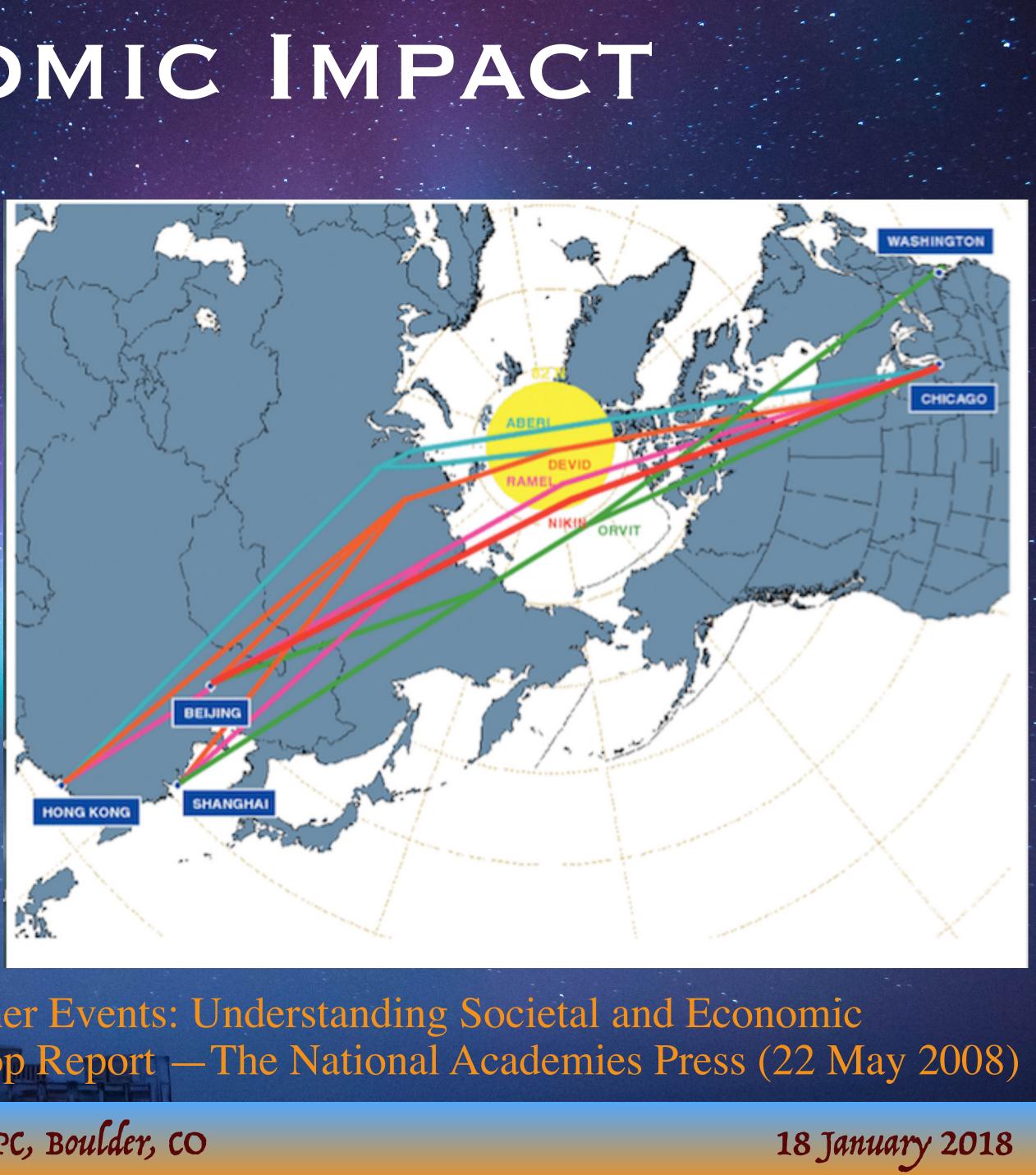


transpolar flights rely on HF radio communications

magnetic storm/polar cap absorption (PCA) — cause ionospheric density disturbances interfere with HF, VHF, UHF radio communications & navigation signals from GPS satellites Severe Space Weather Events: Understanding Societal and Economic Impacts: A Workshop Report — The National Academies Press (22 May 2008)

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G-Scale	Kp	Activity Level	Occurrence Frequency
GO	4 & lower	Below Storm	
G1	5	Minor Storm	1700 per cycle (900 days per cycle)
G2	6	Moderate Storm	600 per cycle (360 days per cycle)
G3	7	Strong Storm	200 per cycle (130 days per cycle)
G4	8	Severe Storm	100 per cycle (60 days per cycle)
G5	9	Extreme Storm	4 per cycle (4 days per cycle)

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KP INDEX & SPACE WEATHER EVENTS

s	cale	Description	LEVEL	EVENT	DATE	Physical measure	Average Frequency (1 cycle = 11 years)
G	5	Extreme	Extreme	Carrington Event widespread disruption of telegraph	1 September 1859	Kp = 9	4 per cycle (4 days per cycle)
G	4	Severe	Extreme	Bastílle Day Event	14 July 2000	Kp = 8, including a 9-	100 per cycle (60 days per cycle)
G	3	Strong	Extreme	Halloween Event Affected airlines, caused power outage, damaged transformers, led astronauts on ISS to take shelter	31 October 2003	Kp = 7	200 per cycle (130 days per cycle)
	Severe		Severe	Hydro-Quebec 9 hour blackout	13 March 1989		
G	2	Moderate	Moderate	Anik-E1 & Anik-E2 failed Disrupted TV & Computer transmission	20/21 January 1994	Kp = 6	600 per cycle (360 days per cycle)
G	1	Minor	Power systems: Weak power grid fluctuations can occur. Spacecraft operations: Minor impact on satellite operations possible. Other systems: Migratory animals are affected at this and higher levels; aurora is commonly visible at high latitudes (northern Michigan and Maine).				1700 per cycle (900 days per cycle)

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Planetary Kp Index (Bartels, 1938)

- refers to a range of geomagnetic activity levels within 3-hr intervals each day (UT)

> Kp varies from 0 to 9, quasi-logarithmically

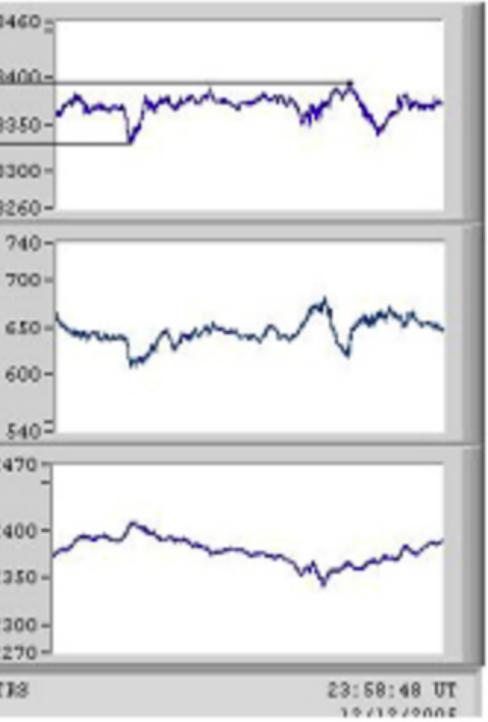
13460 1.340075 nT 13350-13300+ 13260-52470 52400 \$2350 \$2300 52270. 1118

> Petersburg, AK magnetometer data with a 75 nT change in the X-direction (Magnetic North)

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KP INDEX

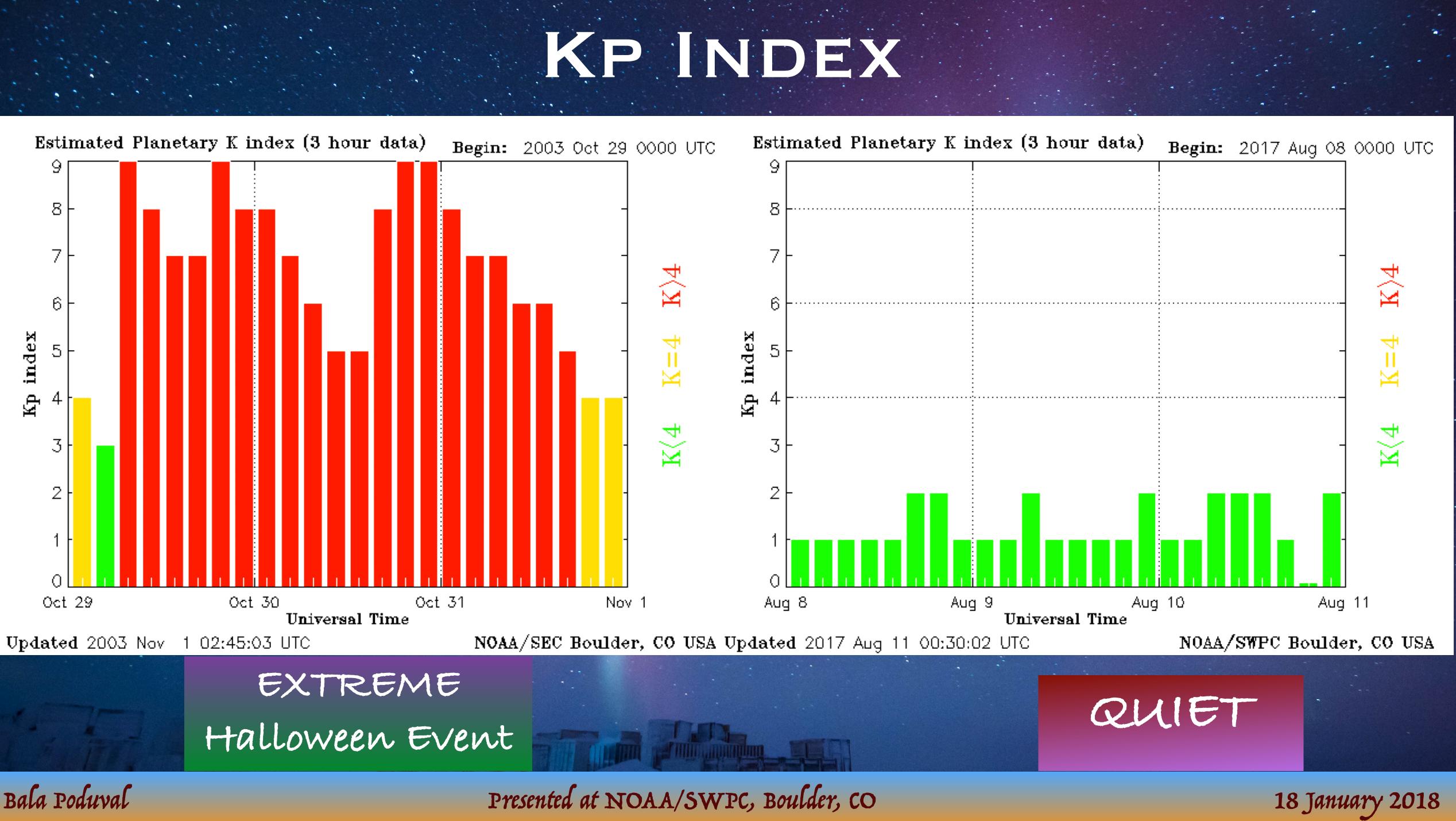


Use this table on the right to convert the difference in the maximum and minimum x-values for today to aK index. The larger the K index, the stormier it is in Earth's magnetic field.

K index	nT
0	0
1	5
2	10
3	20
4	40
5	70
6	120
7	200
8	330
9	>:

-40 -70 -200 -330		
-20 -20 -20 -200 -200		
-20 -20 -20 -200 -200		
-20 -20 -20 -200 -200		
-20 -20 -20 -200 -200		1
-20 -70 -200 -200	diff.	
-20 -70 -200 -200	1-5	
-40 -70 -200 -330	-10	
-70 -200 -330	-20	
-200	-40	1
-200	-70	
-330	-120	
	-200	
-500	-330	, I
	-500	
500	500	

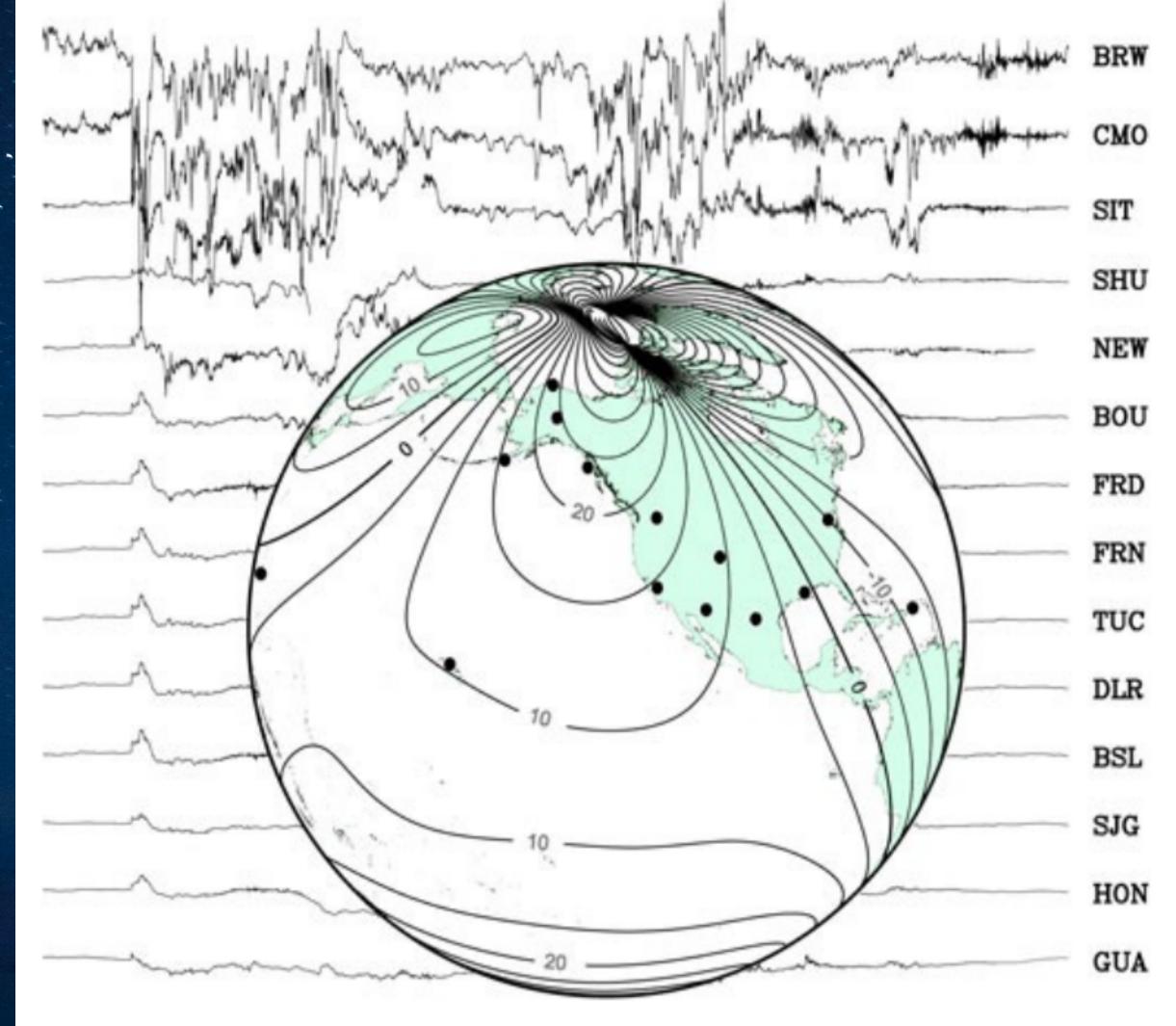




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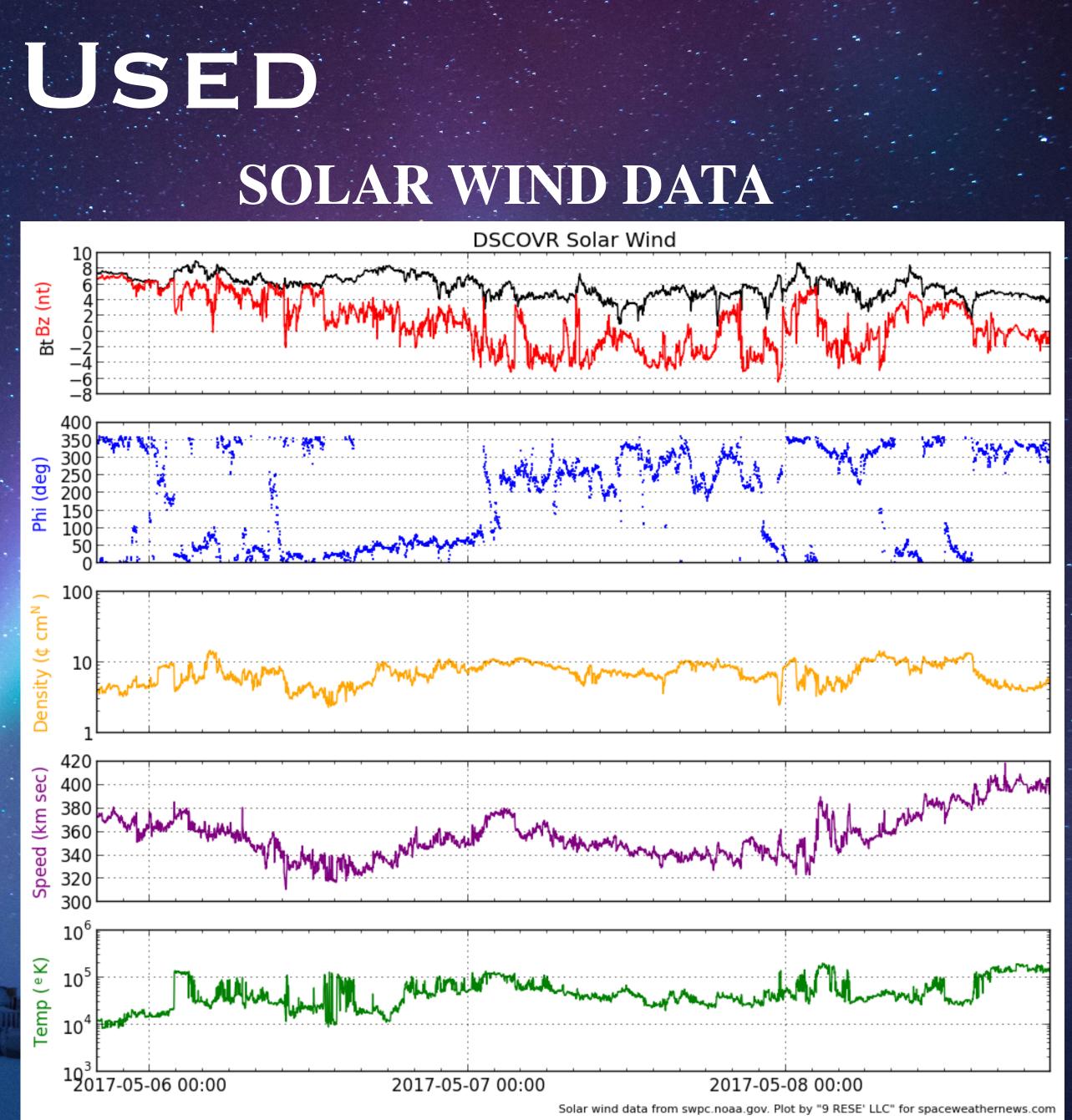
GEOMAG DATA



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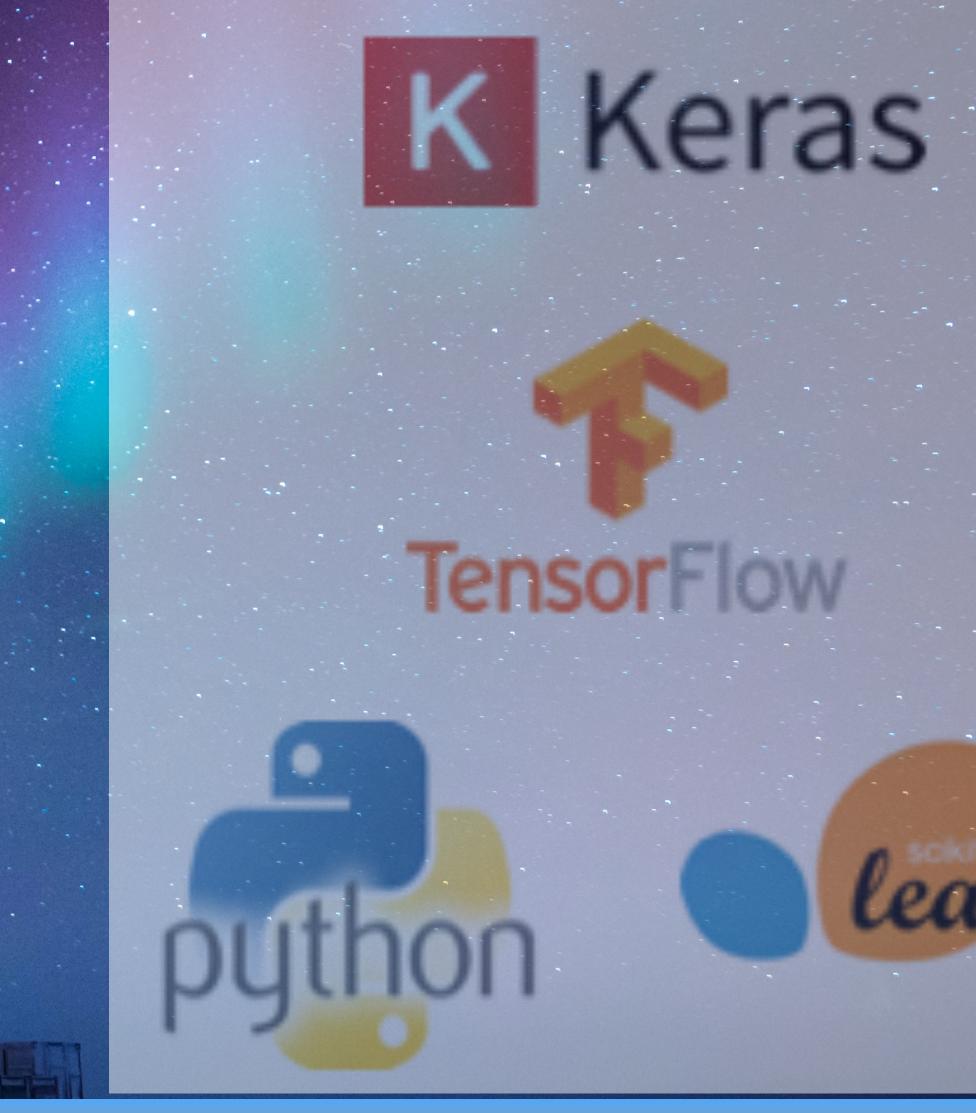
we made use of the industry--standard, open source ML software packages:

- · scikit-learn
- Keras
- · Tensorflow

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MACHINE LEARNING





KERAS

an open source neural network (NN) library written in Python

Scikit-Learn

a free ML library for Python contains various classification, regression & clustering algorithms support vector machines (SVMs) random forests (RF) gradient boosting

designed to operate with Python numerical & scientific libraries NumPy & ScíPy

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MACHINE LEARNING

TensorFlow

an open source software library designed for building & training neural networks to detect and decipher patterns & correlations



supervised machine learning

function approximation

classification & regression

ensemble model

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MACHINE LEARNING

combines several weak learners (usually, decision trees) that have a slight performance advantage over random guessing, to produce a powerful predictive model





Data Used

Geomag, Solar Wind, Kp index

Random Forest Gradient Boosting AdaptiveBoost Extra Trees

Geomag, Solar Wind

Long Short Term Memory (LSTM)

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Recurrent Neural Network



Data Used

Geomag, Solar Wind, Kp index

Gradient Boosting AdaBoost Extra Trees Random Forest

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ENSEMBLE MODELS

These models rank the input features (parameters) according to their importance in making the decision for the output (prediction).

Ensemble



main drawback

of decision trees

they tend to overfit the training data

by combining several trees each tree different from others

each tree does a good prediction by overfitting on part of the data but different from other trees

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ENSEMBLE MODELS

this can be overcome

the overfitting can be reduced

by combining several of such trees average their results

the reduction in overfitting while retaining the predictive power of trees can be proved using rigorous mathematics



Ensemble models considers additive models of the form:

Similar to other boosting algorithms GBRT builds the additive model in a forward stagewise fashion:

 $F_m(x)$

F(

At each stage the decision tree $h_m(x)$ is chosen to minimize the loss function L given the current model F_{m-1} and its fit $F_{m-1}(x_i)$

$$F_m(x) = F_{m-1}(x) + \arg\min_h \sum_{i=1}^n L(y_i, F_{m-1}(x_i) + h(x))$$

The initial model F_0 is problem specific, for least-squares regression one usually chooses the mean of the target values.



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$$x) = \sum_{m=1}^{M} \gamma_m h_m(x)$$

$$F_{m-1}(x) + \gamma_m h_m(x)$$

Gradient Boosting attempts to solve this minimization problem numerically via steepest descent: The steepest descent direction is the negative gradient of the loss function evaluated at the current model F_{m-1} which can be calculated for any differentiable loss function:

$$F_m(x) = F_{m-1}(x) - \gamma_m \sum_{i=1}^n \nabla_F L(y_i, F_{m-1}(x_i))$$

Where the step length γ_m is chosen using line search:

$$\gamma_m = \arg\min_{\gamma} \sum_{i=1}^n L(y_i, F_{m-1}(x_i) - \gamma \frac{\partial L(y_i, F_{m-1}(x_i))}{\partial F_{m-1}(x_i)})$$





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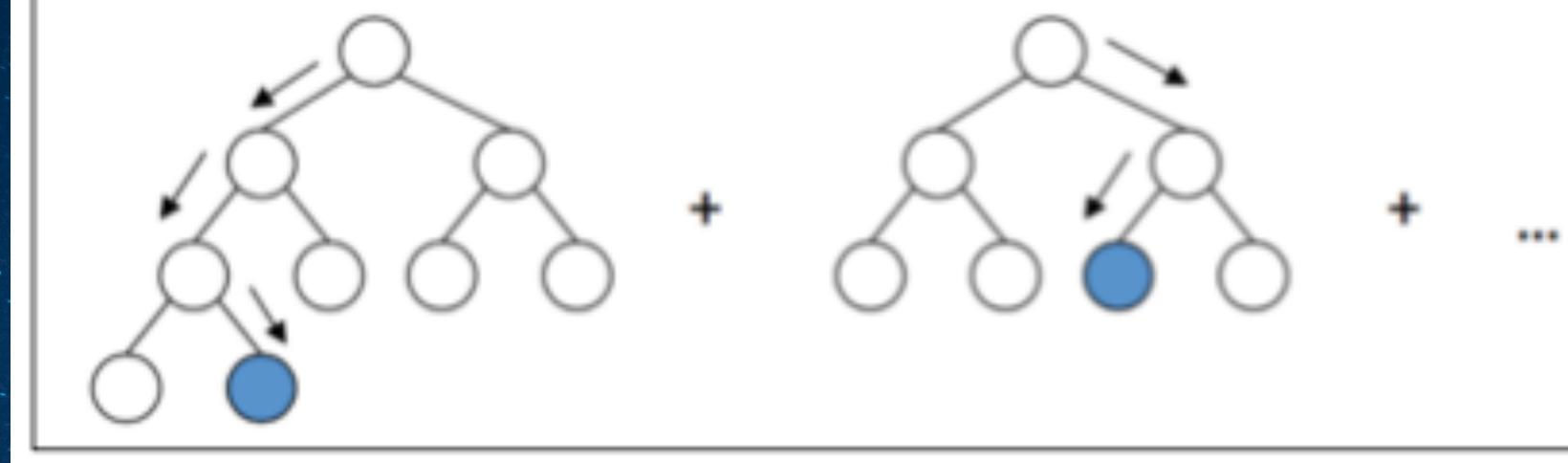
y1 = F(x) [minimizing $(y1 - y)^2$] $F_1(x) = F(x) + h(x)$

Therefore, h(x) = y - F(x) [the residual]

18 January 2018

= y

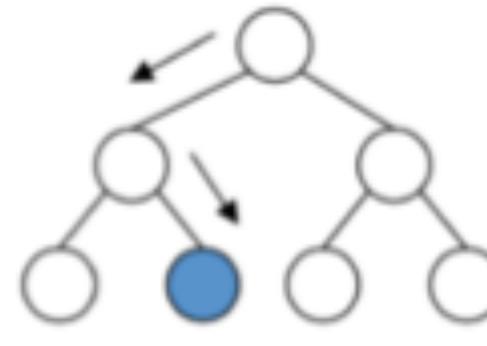




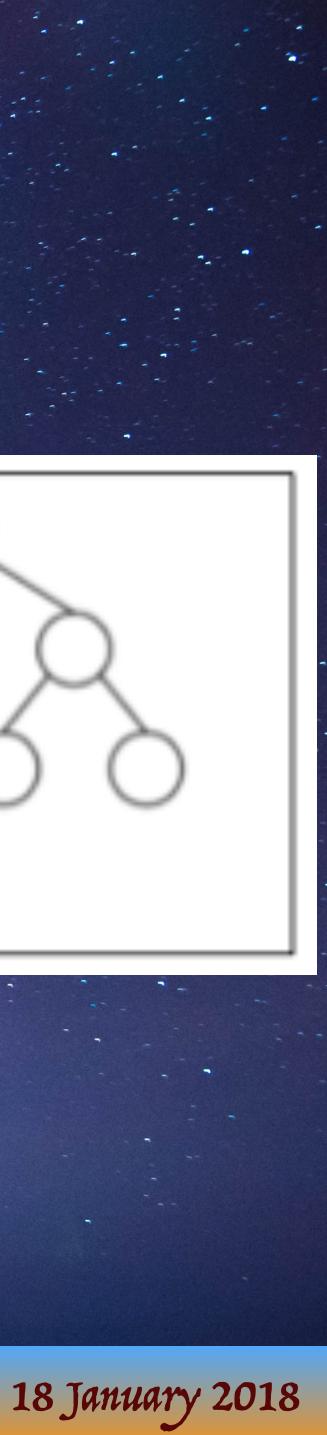


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n_estimator

max_features
 /max_depth

n_features

learning_rate

 the number of
 trees to be built the tree-depth the number of input features

 controls overfitting

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ENSEMBLE MODELS HYPERPARAMETERS

<u>default values of max_features</u>

• for classification

 $max_features = sqrt(n_features)$

for regression

 $max_features = n_features$



Random Forest

trees are determined randomly

• $n_{estimator} = 10$ • max_features = default • $n_{features} = over 50$

RF can be parallelized across multiple CPU cores, especially on large data sets we haven't implemented it in our present study

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ENSEMBLE MODELS HYPERPARAMETERS default values of max_features

for classification $max_features = sqrt(n_features)$ • for regression $max_features = n_features$



Adaptive Boosting

n_estimator = 50
learning_rate = 1
n_features = over 50

 for classification — max_features = sqrt(n_features) for regression $-max_features = n_features$

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ENSEMBLE MODELS HYPERPARAMETERS

ExtraTree

• $n_{estimator} = 10$ max_features = default
n_features = over 50

default values of max_features







Gradient Boosting

trees are built serially & are shallow

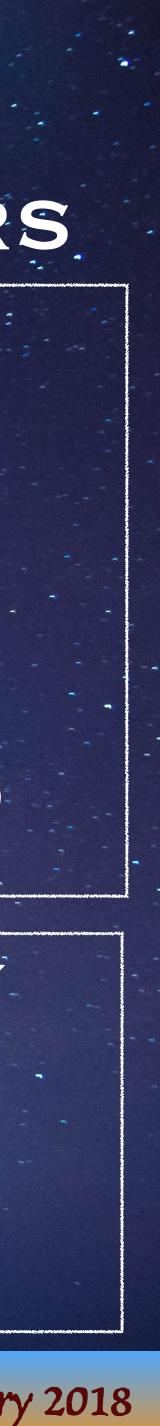
tuning the parameters of GB accurately (the challenge and, therefore, the drawback), it can provide great accuracy the most widely used supervised machine learning method

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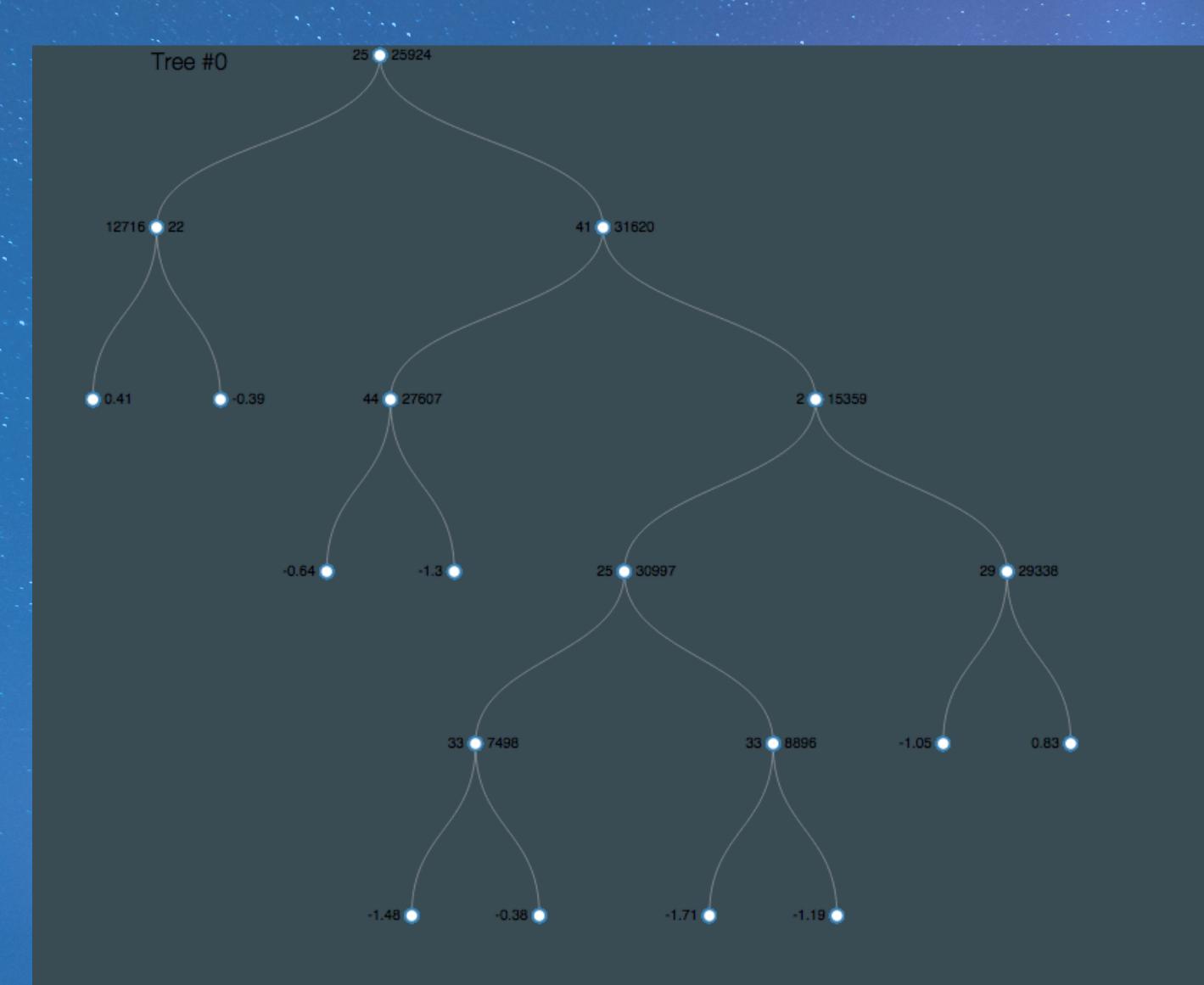
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ENSEMBLE MODELS HYPERPARAMETERS

• $n_{estimator} = 100$ • $max_depth = 3$ • learning_rate = 0.1 \bullet n_features = over 50



GRADIENT BOOSTING



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MEAN SQUARE ERRORS

ML method	1h ahead	3h ahead	6h ahead	sseam
Persist	0.007	0.020	0.025	
Mean	0.046	0.046	0.046	
Median	0.048	0.048	0.048	
Gradient Boosting	<u>50 0.007</u>	0.015	0.021	> 95% confidence level
Adaptive Boost	0.012	0.018	0.032	
Extra Trees	0.009	0.021	0.027	
Random Forest	0.015	0.015	0.026	

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RANKING

1. Kp 2. SW speed 3. IMF strength Geomag X-comp SJG
 SW proton density 6. Geomag X-comp 7. Geomag Z-comp (SHU) 8. Geomag X-comp (HON 9. Geomag Y-comp (H R_7

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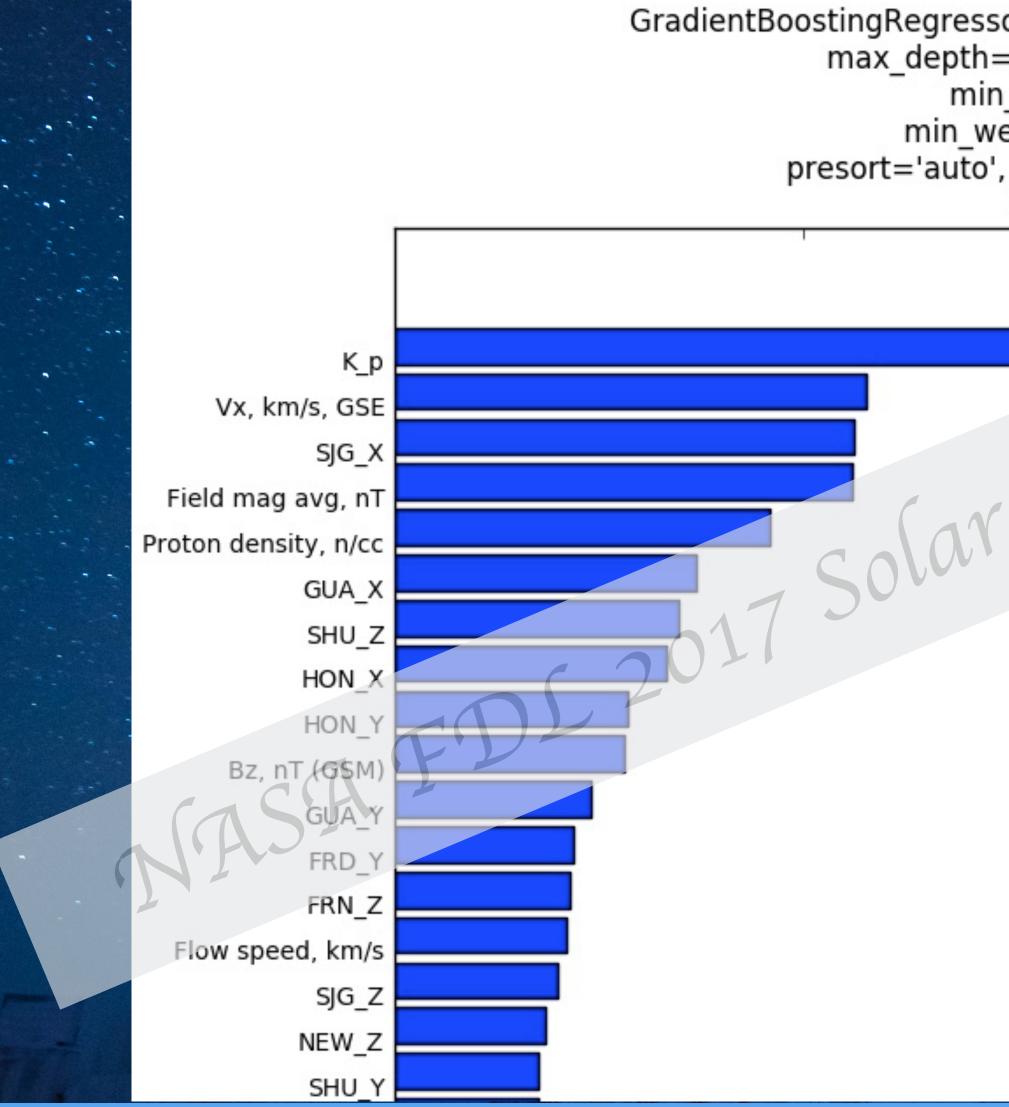
GradientBoostingRegressor(alpha=0.9, init=None, learning_rate=0.1, loss='ls' max depth=3, max features=None, max leaf nodes=None min samples leaf=1, min samples split=2 min weight fraction leaf=0.0, n estimators=100, o', random_state=None, subsample=1.0, verbose=0 warm start=False) for 03h forecast

1. Kp 2. SW speed IMF strength 4. Geomag X-comp SJG
5. SW proton density
6. Geomag X-comp (GUA)
7. Geomag Z-comp (SHU)
8. Geomag X-comp (HON)
9. Geomag Y-comp (HON)
10. IMF Bz TUC Vz, km/s, GSE Plasma beta 0.10 0.05 0.15 Feature Importance

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RANKING



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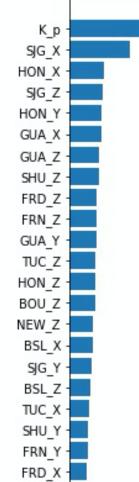
GradientBoostingRegressor(alpha=0.9, init=None, learning_rate=0.1, loss='ls', max_depth=3, max_features=None, max_leaf_nodes=None, min_samples_leaf=1, min_samples_split=2, min_weight_fraction_leaf=0.0, n_estimators=100, presort='auto', random_state=None, subsample=1.0, verbose=0 warm start=False) for 03h forecast

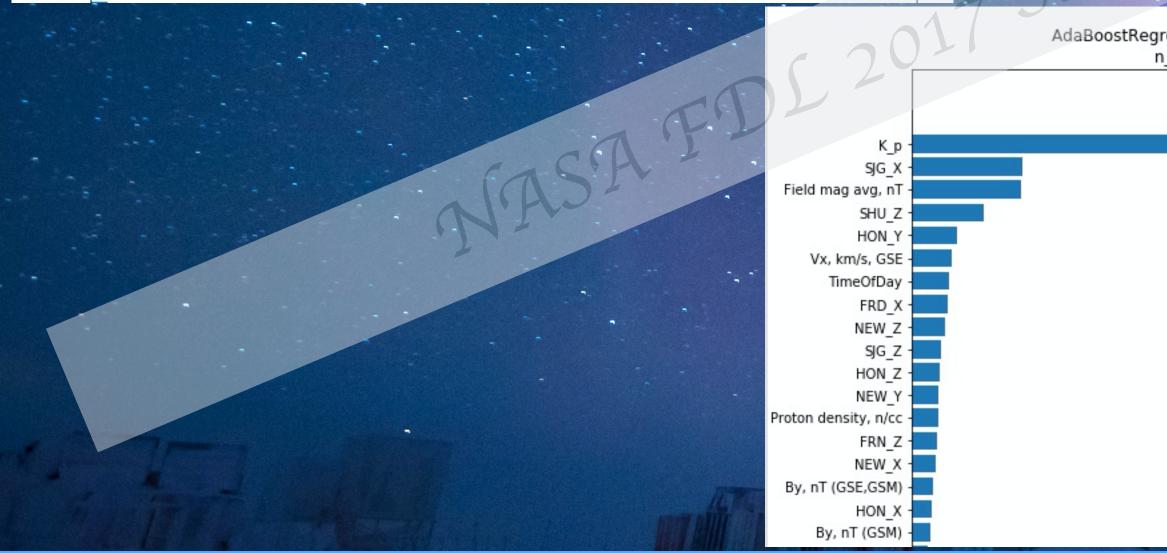
arrent Kp SW speed

- Geomag X-comp SJG
 HMF strength
- 5. SW proton density
 6. Geomag X-comp (GUA)
 7. Geomag Z-comp (SHU)
- 8. Geomag X-comp (HOŃ) 9. Geomag Y-comp (HON)
- 10. HMF BZ



ExtraTreesRegressor(bootstrap=False, criterion='mse', max_depth=None, max_features='auto', max_leaf_nodes=None, min_impurity_decrease=0.0, min_impurity_split=None, min_samples_leaf=1, min_samples_split=2, min_weight fraction leaf=0.0, n_estimators=10, n_jobs=1, oob_score=False, random_state=None, verbose=0, warm_start=False) for 03h forecast





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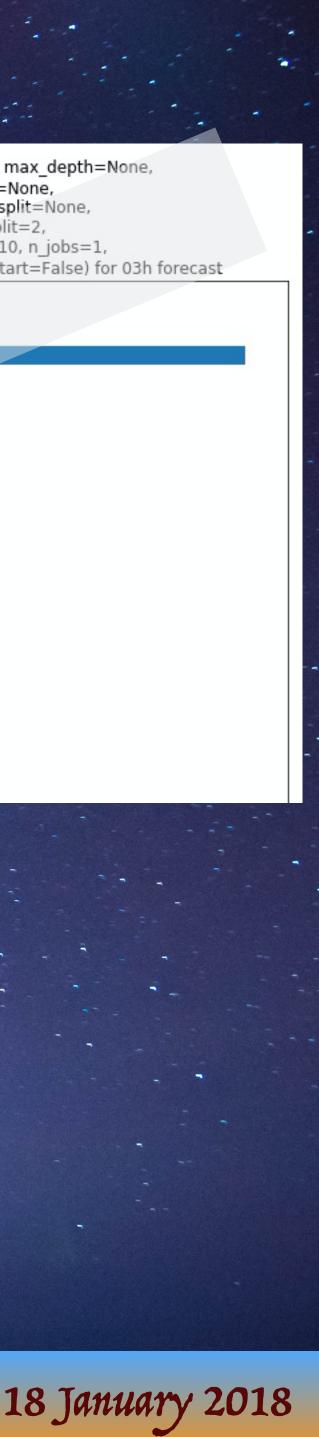
RANKING



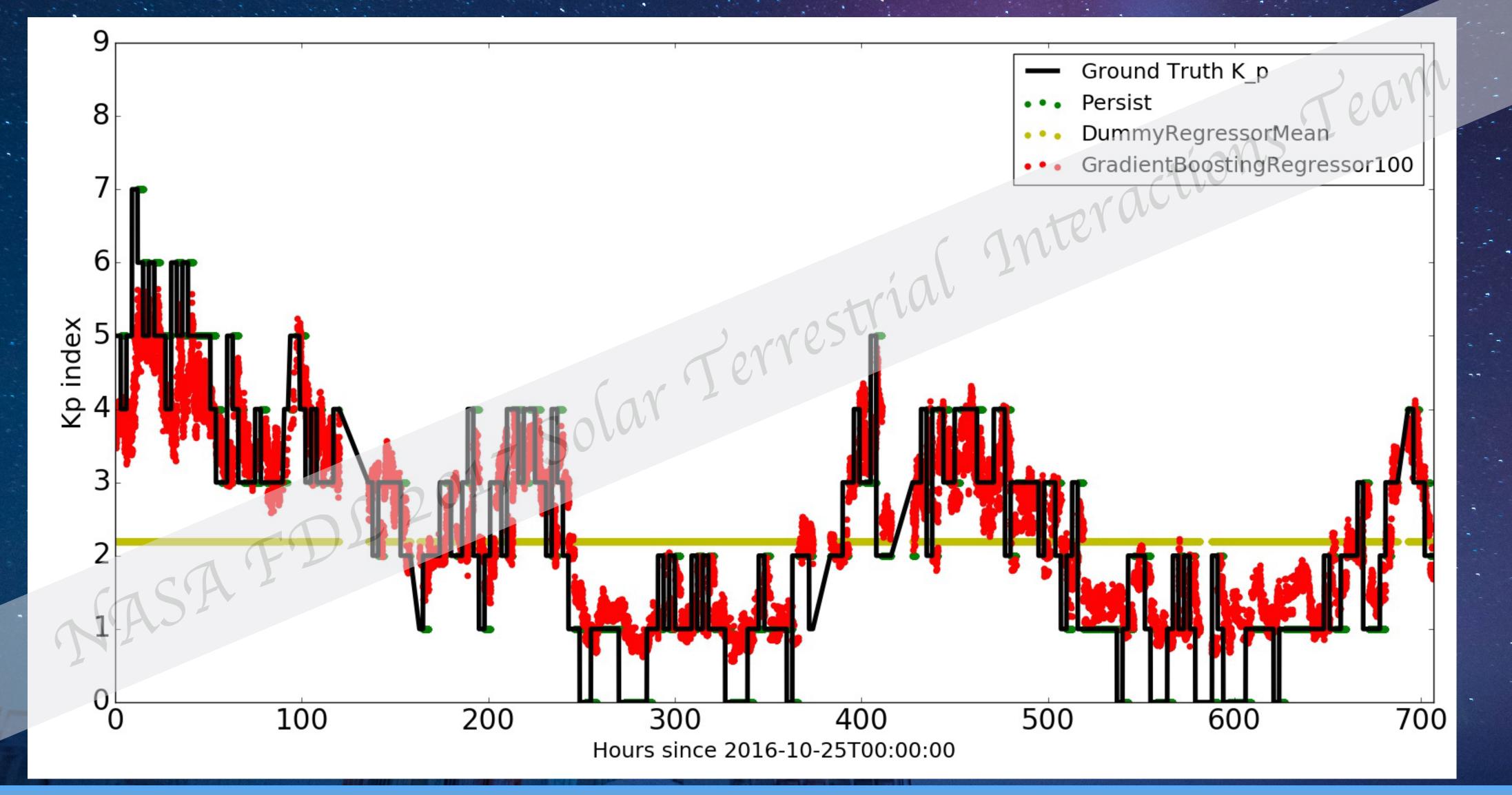
AdaBoostRegressor(base_estimator=None, learning_rate=1.0, loss='linear',







PREDICTED KP



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CONCLUDING REMARKS

input features, according to their order of importance, as raked by GB model:

1. current Kp index 2. solar wind speed, uan, Puerto Ríco, 18°N, 3. <u>X-comp. geomagnetic field - SJG (San J</u> 4. HMF total strength, 5. solar wind proton density, sola 6. X-comp. geomagnetic field - GUA (Guam, 13° N), Z-comp. geomagnetic field - SHU (Shumagin, Alaska, 53° N),
 X-comp. of geomagnetic field - HON (Honolulu, Hawaii, 21° N), 9. Y-comp. of geomagnetic field - HON, 10. HMF z-component, Bz (GSM).

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CONCLUDING REMARKS

the N-S component of the geomagnetic field at lower latitude stations Guam (GUA), Hawaíí (HON), Puerto Rico (SBC

was a total surprise since the ML algorithm was not expected This re to be capable of learning such heuristics without prior knowledge!

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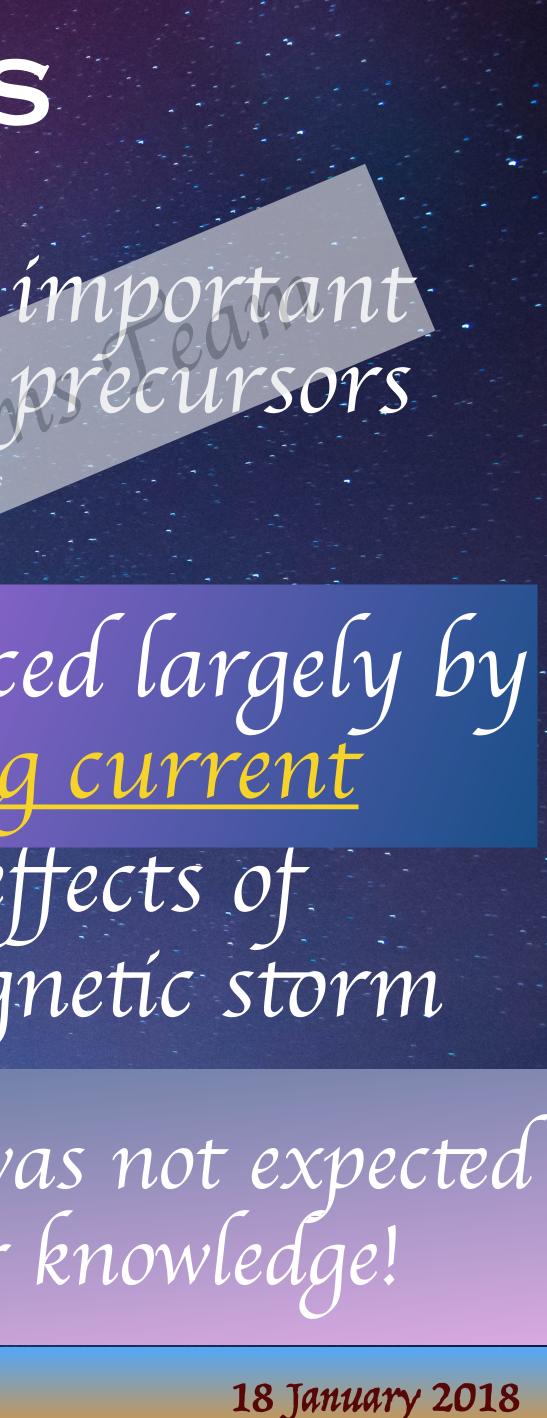
the model

poínts to

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influenced largely by ring current -> the importance of considering the effects of ring current in the prediction of geomagnetic storm

im



CONCLUDING REMARKS

the method can be applied to address other anteractios cope aspects of the socio-economic impact of space weather by predicting the appropriate variable, provided that sufficient data exist in the public domain

Ultimate goal

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To couple the complex and dynamic solar--terrestrial system using AI.

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The Solar Terrestrial Interactions Team with the Unexpected Discovery Award

